

CRANE CALCULATION REPORT

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24/09/2016

1.0 General description

The lifting appliance considered in this calculation report is a jib crane designed to lift various material in off-shore condition.

This crane is foreseen for ARABIYAH HASBAH DEVELOPMENT PROJECT.

The crane is composed by a column, fixed to the platform deck with a slewing double girder boom of fixed length on which travel a trolley.

The net capacity of the crane at the hook is **15 t**.

The movements of the jib crane hook are the classics : **hoisting, trolley travel , slewing**.

Hoisting

Realized with a winch fixed to the structure at one end of the boom , rope deviation sheaves on trolley and return sheave on the other end (outreach) of the boom and hook block.

Cross travel: realized by means of four idle wheels at the corners of the trolley with :

N. 1 trolley translation winch located at one end of the boom

N. 1 return sheave at the other end of the boom

Slewing: realized with base bearing that is the connection element between column and boom and two motor-reducers with pinion engaged on the bearing crown.

2.0 CODES AND STANDARD

The supply and the design have to comply with the technical specification of the SAUDI ARABIAN OIL COMPANY:

JIB CRANE - Tag No.G63-U-130

And for the calculation the following code and standard will be adopted::

API 2C

F.E.M. 1.001 3rd edition(UNI7670)

3.0 LOAD COMBINATION

According to API 2C we take the following combination that is the haviest one because all the forces and factors are taken into account as:

Pay load = 15,0 t

dynamic factor $C_v = 2$

off-lead angle = 0,50°

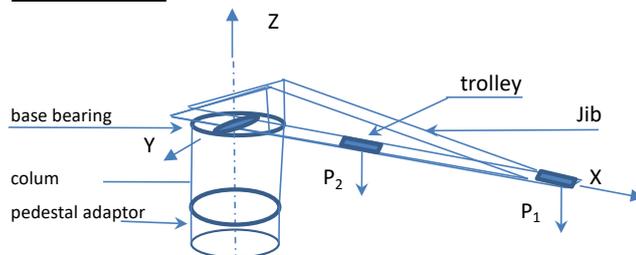
side-lead angle = 0,50°

operational wind = 75,6 Km/h

tangent acceler = 0,2m/s²

centrip. acceler. = 0,03m/s² (negligible)

3.1 CRANE SCHEME



3.2 LOAD CODITION

The conditions of load that will be considered in the calculation are two:

Trolley in **position 1** at the extreme (outreach at **10m** from slew centre) position of the boom

In this position we have the haviest condition for boom structure, base bearing, column and pedestal adaptor

Trolley in **position 2** at the **middle** of the two suspension point of the boom girder

In this position we have to check the stresses of the boom girder were the trolley run.

4 MECHANICAL

In the following we start to calculate the various mechanisms.

4.1 Hoist

The force on the ropes "SWLH" is composed by the pay-load to lift "SWL" plus the hook block dead weight.

$$\text{SWLH} = 150\text{KN} + 5\text{KN} = 155\text{KN}$$

Where:

150 KN = the load to lift (net crane capacity)

5 KN = Hook block dead weight

4.1.1 rope

The minimum braking load "BL" required according to API rules is:

$$\text{BL} = W \cdot \text{DF} / N \cdot E_{rs} = 366\text{KN}$$

Where:

N = 2 reeving (is 2 lines of rope where 1 line go on the drum).

W = SWLH = 155 KN

DF = $2,25 \times C_v = 4,5$

$E_{rs} = (K_b^N - 1) / [K_b^5 \times N \times (K_b - 1)] = 0,952$ Reeving system efficiency

$K_b = 1,02$ for roller bearing

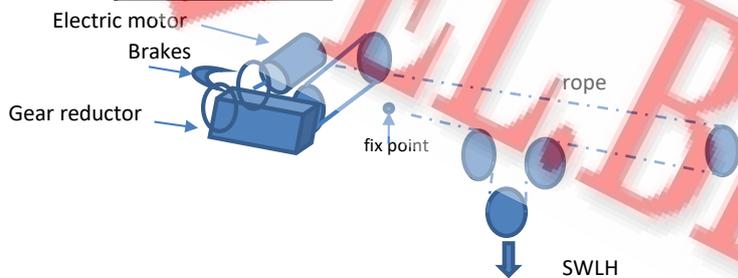
S = 3 total number of sheaves in reeving system

The rope adopted is $\phi 22\text{ mm}$ with BL = 441 KN > 366KN that means DF = 5,5 > 4,5

The sheave pitch diameter is 400 mm > $22 \times 18 = 396\text{ mm}$

The drum pitch diameter is 550 mm > $22 \times 18 = 396\text{ mm}$

Reeving/Hoist scheme



4.1.2 Drum

The drum diameter adopted in function of the geometry is $\phi_D = 550\text{ mm}$

The calculation of the minimum thickness of the drum body, of the drum, shaft and its bearing are in annexes 1, 2, 3. This calculation is done with the UNI rules and not only for resistance but to have a life of 25 years that in this case correspond to 12500 hours of work.

4.1.3 Electric motor

The selection of the motors has been done taking in account the hoisting speed of the load "SWLH" and the efficiency due to the reeving and gearing.

$$N = \text{required power} = \text{SWLH} \times v / (61,2 \times 0,98^3 \times 0,94) = 54,39\text{ Kw}$$

Where:

$$v = \text{hoisting speed} = 19\text{ m/min}$$

The adopted motor has a power of 68 Kw > 54,39 Kw

4.1.4 Brake

The brake service adopted is a double shoes drum brake with electrohydraulic thruster.

The max torque of the mechanism is:

$$M_t \text{ torque of the mechanism} = N_m / \omega = 68.000 / 188,4 = 361 \text{ Nm}$$

Where :

$$N_m = \text{motor power} = 68 \text{ Kw} = 68.000 \text{ W}$$

$$\omega = \text{motor angular speed} = 188,4 \text{ rad/sec} \quad (1780 \text{ rpm}) \quad 188,4$$

The service brake adopted, has $M_f = \text{braking moment} = 800 \text{ Nm} = 2,2 \times M_t > 1,5 \times M_t$

4.1.5 Gear reductor

The reductor gear has been selected taking in account the max torque required.

The max torque required on the low speed(output) shaft is:

$$M_t = SWLH/N \times \phi_D / E_{RS} = 22393 \text{ Nm}$$

The adopted one has a torque of $29500 \text{ Nm} > 22393 \text{ Nm}$

Type: RXP3-814

The theoretical ratio between the in/out shafts is $r = 80,9$

The adopted ratio between the in/out shafts is $r = 80,6$

4.2 TROLLEY TRAVEL

This mechanism is realized by a rope that pull the trolley in the two direction.

The motion is driven by a drum on which the rope are wound on one side and un-wound on the other one.

The drum is coupled with a motoreductor with brake and the rope is fixed to the trolley.

The trolley run on four wheels over two beams that are the boom of the jib crane .

4.2.1 Wheel

This element transmit the actions to the boom via the rails.

The rails adopted are constituted of a steel plate $30 \times 50 \text{ mm}$ $b = 50 \text{ mm}$

The verification of the correct diameter will be done with the Fem rules for the class M5.

Two condition have to be verified: one for the average load and one for the max load.

Trolley weight $P_c = 700 \text{ Kg}$

Wheel diameter $D = 200 \text{ mm}$

According to Fem rules we have:

Coefficient $C_1 = 1,04$ depending from the rpm of the wheel ($V = 10 \text{ m/min}$)

Coefficient $C_2 = 0,8$ depending from the classification

Depending from wheel material $p = 5 \text{ Mpa}$

$$P_{\text{average}} = [(SWLH + P_c) \times 2 + P_c] / 3/4 = 27,6 \text{ KN}$$

$$P_{\text{max}} = (SWLH + P_c) / 4 = 40,5 \text{ KN}$$

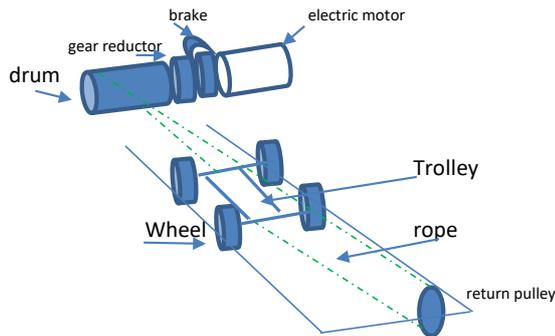
The allowable pressure are:

$$P_{\text{aveall}} = b \times D \times p \times C_1 \times C_2 = 41 \text{ KN} > P_{\text{average}} = 27,6 \text{ KN}$$

$$P_{\text{max all}} = 1,4 \times b \times D \times p = 69 \text{ KN} > P_{\text{max}} = 40,5 \text{ KN}$$

The axle of the wheel and its bearing are verified on **annex 4 and annex 5**

4.2.2 Trolley scheme



4.2.3 Rope

The rope required traction is the action enough to pull the trolley with the load (SWLH) under the influence of friction, acceleration, wind and offlead angle.

The component due to offlead: $SWLH \cdot \sin(0,5^\circ)$	=	1352 N
The force due to a wind of 20 m/sec = $300 \cdot 10$	=	3000 N
The force due to the friction rail/wheel = $(SWLH + Pc) \cdot 0,010$	=	8550 N
The force due to acceleration of $0,1 \text{ m/sec}^2 = 0,15 \cdot (SWLH + Pc)$	=	2430 N
The total force result	Ft =	15332 N

The rope adopted is $\phi 10 \text{ mm}$ with $BL = 90 \text{ KN} > 15,4 \text{ KN}$ that means $DF = 5,8$

The adopted sheave pitch diameter is = $200 \text{ mm} > 18 \times 10 = 180 \text{ mm}$

The adopted drum pitch diameter is $d = 220 \text{ mm} > 18 \times 10 = 180 \text{ mm}$

The calculation of the minimum thickness of the drum body, of the drum, shaft and its bearing are in **annexes 6, 7, 8**. This calculation is done with the UNI rules.

4.2.4 Electric Motor

This motor have to be with a torque and than the force enough to react the total force with a power enough to work with the previous conditions.

$$V = \text{trolley travel speed} = 15 \text{ m/min} \quad 0,25 \text{ m/sec}$$

$$n = \text{motor rot. speed} = 1800 \text{ r.p.m.} \quad 188,40 \text{ rad/sec}$$

$$M_t = \text{torque required} = F_t \times V / n = 20,3 \text{ Nm}$$

The motor is **3,5 Kw** at **1800 rpm** (**188 rad/sec**) with a start torque of **1,5 times** the rated one

$$M_t = \text{start adopted motor torque} = 27,9 \text{ Nm} > 20 \text{ Nm}$$

4.2.5 Brake

The brake adopted is a disc brake with electromagnet thruster.

The max torque of the mechanism is:

$$M_t \text{ max of the mechanism is} = N/n = 19 \text{ Nm}$$

Where :

$$N = \text{motor power} = 3,5 \text{ Kw} = 3500 \text{ W}$$

$$n = \text{angolar speed} = 183 \text{ rad/sec (1750 rpm)}$$

The brake adopted, has $M_f = \text{braking moment} = 40 \text{ Nm} = 2,1 \times M_t > 1,0 \times M_t$

4.2.6 Gear reductor

The reductor gear has been selected taking in account the Fem rules for a class M6.

The max torque required on the low speed shaft of the reductors is:

$$M_t = F_t (\text{pull force}) \times d/2 (\text{drum radius}) = 1687 \text{ Nm}$$

$$\text{The ratio speed of input / speed output shafts is } r = 82,896$$

The adopted one has a nominal torque of **2196 Nm** with a life of 50.000 hours.

Type: EX253MD $r = 85,9$

4.3 SLEWING

This mechanism is realized by means of a base bearing with external crown. The base bearing has been chosen on the basis of the max moment due to the various load and the motion is driven with two motoreductor by pinions engaged with the crown.

The calculation is carried out for the worst condition that is with trolley with full load at 10m, operational wind of 20 m/s, acceleration, side-lead angle and bearing efficiency.

SWLH	=	15500 Kg	
Trolley weight	=	943 Kg	
Slew structure weight	=	22500 Kg	2,15 m
swing circle	=	0,9 m	
Bearing friction factor	=	0,006	
swing speed	=	0,5rpm	
ramp time	=	6 s	
angular acceleration	=	0,009 rad/s	
max SWLH radius	=	10,0 m	
polar inertia SWLH	=	1644300 Kgm ²	
inertia dead weight	=	104006 Kgm ²	

The moment required to swing is the sum of the following actions:

Moment due to the bearing friction	=	2063 Nm
Moment due to acceleration	=	15249 Nm
Moment due to service wind	=	55672 Nm
Moment due to side-lead	=	33144 Nm
The total moment required Mt	=	106128 Nm

4.3.1 Electric Motor

The power required during the start is:

$$N_{\text{swing}} = \frac{M_t \times \omega}{(c_a / c_n) \times \eta} = 3,70 \text{ KW}$$

Where:

$$c_a / c_n = \text{starting torque} = 1,5$$

$$\text{general efficiency } \eta = 0,8$$

The motors are n.2 of 3,5 Kw at 1800 rpm (188 rad/sec) with a start torque of 1,5 times the rated one

$$N_{\text{swing}} = 2 \times 3,5 \text{ Kw} = 7 \text{ Kw} > 3,7 \text{ KW}$$

4.3.2 Brake

The brake adopted is a disc brake with electromagnetic thruster.

The max torque of the mechanism is:

$$M_t \text{ max torque of the mechanism} = N/n = 19 \text{ Nm}$$

Where :

$$N = \text{motor power} = 3,5 \text{ Kw} = 3500 \text{ W}$$

$$n = \text{angular speed} = 188 \text{ rad/sec (1800 rpm)}$$

$$\text{The brake adopted, has } M_f = \text{braking moment} = 30 \text{ Nm} = 1,6 \times M_t > 1,5 \times M_t$$

4.3.3 Gear reducers

The reductor gear has been selected taking in account the Fem rules for a class M6.

The max torque required on the low speed shaft of each of the two reducers is:

$$M_{tr} = (M_t / 2) \times (z_p / z_c) = 7939 \text{ Nm}$$

where:

$$z_p = \text{pinion theet numb.} = 19$$

$$z_c = \text{crown theet numb.} = 127$$

$$\text{The ratio between the input/output shafts is } r = 523,6$$

The adopted one has a nominal torque of 8000Nm with a life of 50.000 hours.

4.3.4 Base bearing

The base bearing is a type with three range of roller and external crown of theet.
The overturning moment taking in account the various factor is:

Moment due to factored load (Cv=2) =	3156 KNm	
Moment due to accelerations =	30 KNm	
Moment due to Wind direction x =	6 KNm	1983,75
Total overturning factored moment	3192 KNm	

Vertical load factored (Cv=2) = **512,0 KN**

The base bearing adopted "191.25.1800.990.41.1502 " see load curve at **annex 9** in this condition with the upmentioned vertical load allow the following moment:

Dynaminc allowable moment $M_{td_{all}}$ =	4200 KNm	>	3192 KNm
Static allowable moment $M_{ts_{all}}$ =	4800 KNm	>	3192 KNm

5.0.0 STRUCTURE

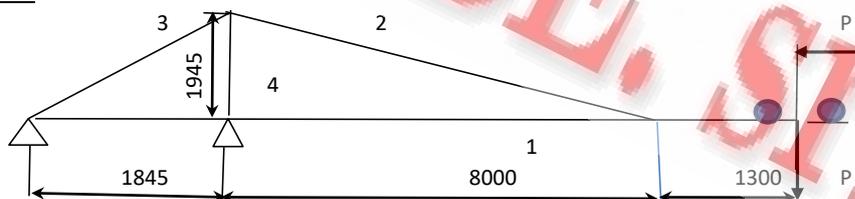
The calculation is carried out taking in account the forces of the mechanical actions and as told at the begining, in a conservative way (See Annex 12).

The material adopted for the structures is S355 J2 (sometimes called also Fe 510D) that, according to API and others codes, being $\sigma_y/\sigma_u < 0,7$ the allowable stress are:

	operational	with wind	exceptional
$\sigma_{all} =$	240 N/mm ²	270 N/mm ²	300 N/mm ²
$\tau_{all} =$	140 N/mm ²	156 N/mm ²	174 N/mm ²

5.1.0 Jib

5.1.1 Jib Scheme



5.1.2 POSITION 1

Girder 1 Two IPE 400 coupled

$\sigma_{max} = 197N/mm^2$	<	$\sigma_{all} = 240N/mm^2$
$\tau_{max} = 53N/mm^2$	<	$\tau_{all} = 140N/mm^2$
$\sigma_{id} = 217N/mm^2$	<	$\sigma_{all} = 240N/mm^2$

The stresses are inclusive of all the actions and factors (Cv=2) and the allowable stress is bigger than the max permissible because the actions include also the wind but, to be more conservative, we take in account the stress allowable lower one.

Tie rod 2

This element is only tensioned and is built with a pipe $\phi 152$ mm thikness 12 mm

$\sigma_{max} = 157N/mm^2$	<	$\sigma_{all} = 240N/mm^2$
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Tie rod 3

This element is only tensioned and is built with a pipe ϕ 152 mm thickness 12 mm

$$\sigma_{\max} = 189\text{N/mm}^2 < \sigma_{\text{all}} = 240\text{N/mm}^2$$

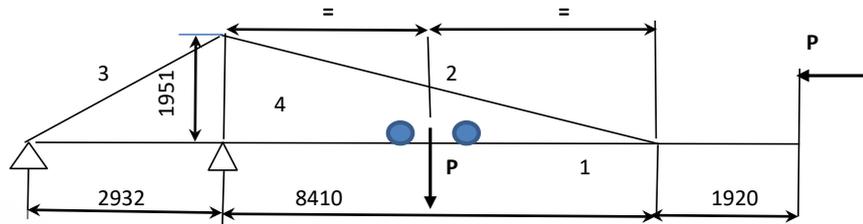
Compressed item 4

This element is only compressed and is built with a pipe ϕ 152 mm thickness 12 mm

$$\sigma_{\max} = 146\text{N/mm}^2 < \sigma_{\text{all}} = 240\text{N/mm}^2$$

5.1.3 POSITION 2

With the pay load in the middle of the boom as shown we have the following stresses:



Girder 1

$$\begin{aligned} \sigma_{\max} &= 210\text{N/mm}^2 < \sigma_{\text{all}} = 240\text{N/mm}^2 \\ \tau_{\max} &= 26\text{N/mm}^2 < \tau_{\text{all}} = 140\text{N/mm}^2 \\ \sigma_{\text{id}} &= 215\text{N/mm}^2 < \sigma_{\text{all}} = 240\text{N/mm}^2 \end{aligned}$$

The stresses are inclusive of all the actions and factors ($C_v=2$) and the allowable stress is bigger than the max permissible because the actions include also the wind, but to be more conservative we take the allowable lower one.

Tie rod 2

This element is only tensioned and is built with a pipe ϕ 152 mm thickness 12 mm

$$\sigma_{\max} = 77\text{N/mm}^2 < \sigma_{\text{all}} = 240\text{N/mm}^2$$

Tie rod 3

This element is only tensioned and is built with a pipe ϕ 152 mm thickness 12 mm

$$\sigma_{\max} = 92\text{N/mm}^2 < \sigma_{\text{all}} = 240\text{N/mm}^2$$

Compressed item 4

This element is only compressed and is built with a pipe ϕ 152 mm thickness 12 mm

$$\sigma_{\max} = 89\text{N/mm}^2 < \sigma_{\text{all}} = 240\text{N/mm}^2$$

5.2.0 BASE bearing bolting

According to the API 2C rules, the ultimate strenght criteria of the bolts have to satisfied the following:

$$P = 4 \cdot M / N_b \cdot D - H / N_b = 552,0 \text{ KN}$$

where:

P = max allowable force in one bolt

$$M = 3,75 \times \text{total overtur factored mom.} = 11970 \text{ KNm}$$

N_b = number of bolts = 48

D = bolts circle diam. = 1,685 m

$$H = 3,75 \times \text{vertical factored force} = 1920,0 \text{ KN}$$

$$A = \text{resistance section of bolt M30} = 561\text{mm}^2$$

$$\sigma_{\text{bolt}} = 984\text{N/mm}^2$$

$$\sigma_{\text{all}} = 1000\text{N/mm}^2 > \sigma_{\text{bolt}}$$

So we can say that the **bolts class 10.9** is acceptable.

Flange plate edge column calculation see annex 10

5.3.0 COLUMN

The verification will be carried out for the section at the base where the column is welded to the deck.

Dc = column outer diameter = 1800 mm
 th = column thickness = 20 mm
 Jx = inertia moment = 4427764 cm⁴
 Wx = resistant mom. = 49197 cm³
 Ac = section area = 111784 mm²

The actions on this element is the same of the base bearing increased by the moment of transport generated from the wind, acceleration and its the vertical dead load.

Furthermore the API rules foreseen for the crane support structure an additional factor PH that applies to the factored load.

PH = 1,56 - SWLH/900000 = 1,56

Where value of PH must be not less than 1,2 **but not greater than 1,5** so in our case :

PH = 1,5

The vertical factored action and moment included the additional factor PH result:

Hc = 937 KN

Mc = 4788 KNm

$\sigma_b \text{ max} = 97 \text{ N/mm}^2 < \sigma_{\text{all}} = 240 \text{ N/mm}^2$

$\sigma_c \text{ max} = 8 \text{ N/mm}^2 < \sigma_{\text{all}} = 240 \text{ N/mm}^2$

$\tau \text{ max} = \text{negligible}$

Buckling verification

$\sigma_{bb} = \sigma_y (1 - \sigma_y / (4 K_b E (th/Dc)^2)) = 299,3 \text{ N/mm}^2$

$\sigma_{cb} = K_c E (th/Dc)^2 = 129,6 \text{ N/mm}^2$

$\tau_b = 0,58 \sigma_y (1 - 0,58 \sigma_y / (4 K_s E (t/b)^2)) = 165,0 \text{ N/mm}^2$

F = 0,67 (stress factor)

$\sigma_b \text{ max} = 97 \text{ N/mm}^2 \text{ N/mm}^2 < \sigma_{bb} \cdot F = 200,5 \text{ N/mm}^2$

$\sigma_c \text{ max} = 8 \text{ N/mm}^2 \text{ N/mm}^2 < \sigma_{cb} \cdot F = 86,9 \text{ N/mm}^2$

$\tau \text{ max} = 0 \text{ N/mm}^2 < \tau \cdot F = 110,6 \text{ N/mm}^2$

$(\sigma_{\text{max}b} / \sigma_{bb})^2 + (\sigma_{\text{max}c} / \sigma_{cb})^2 + (\tau_{\text{max}} / \tau_b)^2 = 0,11 < F$

5.3.1 COLUMN BOLTING

For this verification **as conservative action** we use the same method of the base bearing bolting.

According to the API 2C rules, the ultimate strength criteria of the bolts have to satisfied the following:

$P = 4 \cdot M / Nb \cdot D - H / Nb = 535,5 \text{ KN}$

where:

P = max allowable force in one bolt

$M = 3,75 \times \text{total overturn factored mom.} = 11970 \text{ KNm}$

Nb = number of bolts = 48

D = bolts circle diameter = 1,823 m

H = 3,75 x vertical factored force = 2343 KN

A = resistance section of M30 = 561 mm²

$\sigma_{\text{bolt}} = 95 \text{ N/mm}^2$

$\sigma_{\text{all}} = 1000 \text{ N/mm}^2 > \sigma_{\text{bolt}}$

So we can say that the bolts **class 10.9** is acceptable.

Flange plate edge column calculation not necessary because is the same of base bearing.

5.4.0 **SEISMIC**

According to API rules we can assume that due to a very low probability of simultaneous occurrence of a design seismic event at the time of the crane being used for a maximum rated lift, a reduced crane load may be considered simultaneous with the design seismic event.

In absence of such a study, a load producing 2/3 Of the rated crane overturning moment capacity shall be considered.

The max acceleration of 0,125 g of the site condition is lower than the load reduction that we have taking in account the upmentioned consideration .

Furthermore the stress in the various structure members has a value with a significant margin in front of the allowable stress that in this case is the exceptional one.

So, with this consideration we can assume satisfied this verification.

5.5.0 **TRANSPORTATION CONDITION**

The transportation loads taken in account are:

Barge motion input:

Roll = 12,5 deg

Pitch = 5,725 deg

Heave = 0,255g = 2,5 m /sec²

Wind = 145 Km/h

Accelerations

X(G)

Y(G)

Z(G)

+/- 0,23

+/- 0,49

+/- 0,23

The stresses in the structures of the cranes, with the actions above mentioned are max 68N/mm²

Also the base bearing and column bolting are understressed in front of the working verification.

The max stress in the bolt is 180 N/mm² according to API 2C rules.

